

# Behavioral Mechanism Design

## Lecture 1/2

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# Outline

## ① Lecture 1: Theory

- ① Mechanism Design History (Briefly)
- ② Mechanism Design Theory
- ③ Behavioral M.D. Methodology

## ② Lecture 2: Applications

- ① Stable Public Goods Mechanisms
- ② Prediction Markets
- ③ Contracting within NASA

# The Socialist Calculation Debate

- Marx & Friends (1800s-1918)
  - The labor theory of value
  - To revolt or not (and other annoying details)
  - How to deal with the incentive issues?
- von Mises, von Hayek & Friends (1920–1945)
  - Capital prices give info on productivity & scarcity
  - Example: oil vs. wine
  - Consumption-goods prices give info on welfare
  - Prices coordinate decentralized production plans
  - Opponents: P.O. = sol'n to system of eq's
  - Response: Too much info needed to solve the system

# The Socialist Calculation Debate

- Oscar Lange & Abba Lerner (1934-1938)
  - Market Socialism: Admits prices are needed
  - Social planner 'simulates' markets (tatonnement)
  - Prices are just accounting tools (incentives??)
  - Problem: no financial markets to assess investment
  - Lange: Stalin-Roosevelt & Polish head-of-state

Theory all rested on Pareto, Edgeworth, etc.

# Leonid Hurwicz

- Born 1918, right before the Bolshevik Revloution
- 1938: Law degree at Warsaw. No econ degree.
- 1938: LSE under Hayek, met with Mises
- 1941: RA to Samuelson & Lange
- 1942-46: Research associate under Marschak & Koopmans
- 1959: First publication on mechanism design theory
- 1961-2008: Minnesota

# Mechanism Design Setup

- Outcome space:  $X$
- Preferences over  $X$ :  $u_i(x|\theta_i)$
- Type space:  $\Theta = \times_{i=0}^n \Theta_i$  ( $0 = \text{planner}$ )
- Message space:  $M = \times_{i=0}^n M_i$
- Adjustment rule:  $m_i^t = \alpha_i(m^{t-1}, \theta_i)$
- Steady-state message:  $m^* = \alpha(m^*, \theta)$
- Equilibrium correspondence:  $\mu : \Theta \rightarrow M$   
 $\mu(\theta) \subseteq M$  identifies steady-state messages
- Outcome function:  $g : M \rightarrow X$
- MECHANISM:  $(M, g)$
- ASSUMED:  $\alpha$  ( and/or  $\mu$  )

# The Competitive Mechanism

- $X$  = all possible net trade vectors
- $M_i$  ( $i > 0$ ) = excess demands for each good
- $M_0$  = prices for each good
- $\alpha_0(m^{t-1})$  = period- $t$  tatonnemont prices
- $\alpha_i(m^{t-1})$  = excess demand given period- $t - 1$  prices
- $\mu_0(\theta)$  = Walrasian price vector
- $\sum_i \mu_i(\theta) = \vec{0}$
- $g(m^*) = (m_1^*, \dots, m_n^*)$
- Satisfactory (Pareto optimal outcomes)
- Privacy-preserving
- Informationally efficient (ask Mark)

## The Static Approach

- Typically remove the planner (no pvt info, no adjusting)
- $\mu$  = set of (Nash/DomStrat/Bayes)-equilibrium strategies of the induced game:
  - Players:  $\{1, \dots, n\}$
  - Strategies:  $M_i$
  - Utility:  $u_i(g(m)|\theta_i)$
- Predicted outcomes:  $g(\mu(\theta)) \subseteq X$

# Social Choice Correspondences

- What is the objective of the social planner??
- Abstract notion:  $f(\theta) \subseteq X$  (for any  $\theta \in \Theta$ )
- $f =$  social choice correspondence (SCC) or function (SCF)
- Examples:
  - Pareto optimal  $x$
  - Planner's most-preferred  $x$
  - 'Equitable'  $x$  (egalitarian, envy-free, etc.)

# Implementation & Mechanism Design

- A mechanism  $(M, g)$  fully implements a SCC  $f$  under  $\mu$  if, for all  $\theta \in \Theta$ ,

$$g(\mu(\theta)) = f(\theta)$$

- Partial implementation:

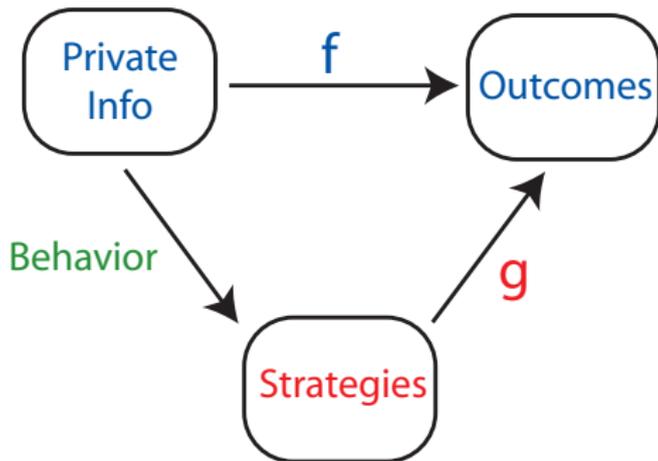
$$g(\mu(\theta)) \subseteq f(\theta)$$

or even

$$g(\mu(\theta)) \cap f(\theta) \neq \emptyset$$

- 'Mechanism design' vs. 'implementation'

# The Mount-Reiter Diagram



# Dominant Strategy Implementation

- Strongest solution concept: dominant strategies
- Gibbard (73) & Satterthwaite (75): Revelation principle
  - Suppose  $\Gamma = (M, g)$  has a DSE  $\mu_\Gamma(\theta)$  for every  $\theta$
  - Consider new mechanism:  $\Gamma' = (\Theta, h)$  where
    - Agents announce a type ( $m_i \in \Theta_i$ )
    - Mechanism picks  $h(\theta) = g(\mu_\Gamma(\theta))$
  - Idea:  $\Gamma'$  plays  $\mu_\Gamma$  for you
  - $\mu_\Gamma$  is a DSE in  $\Gamma \Rightarrow \theta$  is a DSE in  $\Gamma'$

## Multiple Equilibrium Problems

$$X = \{a, b, c, d, e, p, q, r\}$$

$$\theta_1 = \begin{bmatrix} q \\ a, c, e \\ d, b, p \\ r \end{bmatrix}$$

$$\theta_2 = \begin{bmatrix} r \\ d, a, e \\ b, c, p \\ q \end{bmatrix}$$

$$\theta'_1 = \begin{bmatrix} c, b, p \\ a, d, e \\ q, r \end{bmatrix}$$

$$\theta'_2 = \begin{bmatrix} d \\ b, c \\ a \\ e, p, q, r \end{bmatrix}$$

$\Gamma$	B1	B2	B3
A1	a	d	e
A2	c	b	p
A3	a	b	e

$\Gamma'$	$\hat{\theta}_2$	$\hat{\theta}'_2$
$\hat{\theta}_1$	e	b
$\hat{\theta}'_1$	p	b

$$\begin{aligned} f(\theta_1, \theta_2) &= \{a, e\} \\ f(\theta'_1, \theta_2) &= \{c, p\} \\ f(\theta_1, \theta'_2) &= \{b, d\} \\ f(\theta'_1, \theta'_2) &= \{b\}. \end{aligned}$$

$\Gamma''$	$\hat{\theta}_2$	$\hat{\theta}'_2$
$\hat{\theta}_1$	a	d
$\hat{\theta}'_1$	c	b

## Revelation Principle Cont'd

- Revelation principle holds iff  $\mu_i(\theta)$  depends only on  $\theta_i$ 
  - DSE & BNE: yes
  - Nash, SPNE, IESDS: no

$$X = \{a, b, c, d\}$$

$$\theta_1 = \begin{bmatrix} a \\ c \\ d \\ b \end{bmatrix} \quad \theta_2 = \begin{bmatrix} c \\ d \\ a \\ b \end{bmatrix} \quad \theta'_2 = \begin{bmatrix} b \\ a \\ d \\ c \end{bmatrix}$$

$$f(\theta_1, \theta_2) = \{a\}$$

$$f(\theta_1, \theta'_2) = \{d\}$$

$\Gamma$	L	R
U	a	b
D	c	d

$\Gamma'$	$\hat{\theta}_2$	$\hat{\theta}'_2$
$\hat{\theta}_1$	a	d

## Dom. Strat. Results

- $f$  is dictatorial if  $\exists i$  s.t.  $\forall \theta$

$$f(\theta) \in \arg \max u_i(x|\theta_i)$$

- Gibbard-Satterthwaite: When all strict preferences are admissible, if  $|X| \geq 3$  and if  $f$  can be implemented in DSE then  $f$  is dictatorial.
- Zhou 91 & others: Also true for 'economic' environments

## DSE: Quasilinear Prefs

- Quasilinear prefs:  $u_i(x, t_i | \theta_i) = v_i(x | \theta_i) + t_i$
- Roberts 79: If  $|X| \geq 3$ , all quasilinear prefs are admissible, and  $f$  can be implemented in DSE then  $\exists (\lambda_1, \dots, \lambda_n) \geq 0$  and  $v_0$  s.t.

$$x(\hat{\theta}) = \arg \max_{x \in X} \left[ v_0(x) + \sum_i \lambda_i v_i(x | \hat{\theta}_i) \right]$$

and if  $\lambda_i > 0$  then

$$t_i(\hat{\theta}) = \frac{1}{\lambda_i} \left( \left[ v_0(x(\hat{\theta})) + \sum_{j \neq i} \lambda_j v_j(x(\hat{\theta}) | \hat{\theta}_j) \right] + h_i(\hat{\theta}_{-i}) \right)$$

- Groves (1973) mechanisms:  $\lambda_i = 1$  &  $v_0 \equiv 0$
- Green & Laffont

## VCG Mechanism

- Groves mechs need not be balanced
  - Ex:  $h_i(\hat{\theta}_{-i}) = \$1,000,000\forall i$
- Clarke 71: use

$$h_i(\hat{\theta}_{-i}) = - \max_{x \in X} \left[ v_0(x) + \sum_{j \neq i} \lambda_j v_j(x | \hat{\theta}_j) \right]$$

- Guarantees  $t_i(\hat{\theta}) \leq 0$
- Vickrey 1961

## Issues with VCG

- Generally not fully efficient (not balanced)
- Often not individually rational (right notion??)
- Distribution of taxes can be highly inequitable
- The equilibrium may be 'weak' & other NE may exist
- May be difficult to communicate preferences
- Agents may have reasons to conceal their type
- Assumes no bankruptcy/liquidity constraints
- Finding  $\arg \max_{x \in X} \sum_i v_i(x | \hat{\theta}_i)$
- Shill bidding can be advantageous
- Collusion can be profitable
- Dynamic allocation problems

# Bayesian Implementation

- Agents' types are drawn from  $\rho_i(\theta_i)$
- Each  $\rho_i$  is common knowledge (incl. the planner)
- General preferences: see Jackson 91
- Quasilinear prefs: d'Aspremont & Gerard-Varet

- Let  $W_i(\theta_i) = E_{\theta_{-i}}[\sum_{j \neq i} v_j(x(\theta_i, \theta_{-i}) | \theta_j)]$

- Transfer:

$$t_i(\theta) = W_i(\theta_i) - \frac{1}{n-1} \sum_{j \neq i} W_j(\theta_j)$$

- Sum of transfers = zero

# Nash Implementation

- Partial implementation is easy:
- Each agent reports  $m_i = (\hat{\theta}_1, \dots, \hat{\theta}_n)$
- If  $m_1 = m_2 = \dots = m_n$  then select  $f(m_1)$
- If any disagreement, shoot everyone
- 'Truth-telling' is an equilibrium, giving  $f(\theta)$
- Consistent lies are also equilibria, giving  $f(\theta')$
- The main problem is these bad equilibria

## Maskin Monotonicity

- Let  $L_i(x, \theta_i) = \{y \in X : u_i(x|\theta_i) \geq u_i(y|\theta_i)\}$
- $f$  is monotonic if  $x \in f(\theta)$  and  $L_i(x|\theta_i) \subseteq L_i(x|\theta'_i) \forall i$  implies  $x \in f(\theta')$ .
- If  $f$  can be fully implemented in NE then  $f$  is monotonic
- Suppose  $f$  is not monotonic. Then  $\exists x, \theta$  with  $x \in f(\theta)$  and  $L_i(x|\theta_i) \subseteq L_i(x|\theta'_i) \forall i$  but  $x \notin f(\theta')$
- But if  $x$  is getting better for everyone, then the alternatives players could get by deviating aren't any better under  $\theta'$
- Thus, NE under  $\theta$  are NE under  $\theta'$
- Full implementation requires that  $x \in f(\theta')$

## Maskin's Mechanism

- $m_i = (\hat{\theta}^i, \hat{x}^i, k^i)$
- If all  $m_i$  agree and  $\hat{x} \in f(\hat{\theta})$  then pick  $\hat{x}$
- If one person  $j$  differs:
  - If  $j$ 's deviation is good for himself (by  $\hat{\theta}^j$ ), pick  $\hat{x}^j$
  - If  $j$ 's deviation is bad for himself (by  $\hat{\theta}^j$ ), pick  $\hat{x}^i$
- If two or more disagree, pick  $\hat{x}^{\arg \max_i k^i}$
- Clearly, 'truth-telling' is a NE
- Bad equilibria eliminated (ex: coordinated lie)



## Groves-Ledyard 1977

$$m_i \in \mathbb{R}^1$$

$$y(m) = \sum_i m_i$$

$$t_i(m) = q_i(m_{-i})y(m) + g_i(m), \text{ where}$$

$$q_i(m_{-i}) = \frac{\kappa}{n}$$

$$g_i(m) = \frac{\gamma}{2} \left[ \frac{n-1}{n} (m_i - \mu_{-i})^2 - \sigma_{-i}^2 \right]$$

$$\mu_{-i} = \frac{1}{n-1} \sum_{j \neq i} m_j \quad \sigma_{-i}^2 = \frac{1}{n-2} \sum_{j \neq i} (m_j - \mu_{-i})^2$$

Notes:

- Implements PO outcomes
- Not Lindahl  $\Rightarrow$  not IR (see Hurwicz 79)

$$m_i \in \mathbb{R}^1$$

$$y(m) = \sum_i m_i$$

$$t_i(m) = q_i(m_{-i})y(m) + g_i(m), \text{ where}$$

$$q_i(m_{-i}) = \frac{\kappa}{n} + m_{i+1} - m_{i+2}$$

$$g_i(m) \equiv 0$$

Notes:

- Implements Lindahl allocations ( $\Rightarrow$  IR)
- Uses only one dimension
- Agents are 'price-taking'

$$m_i = (s_i, z_i) \in \mathbb{R}^2$$

$$y(m) = \frac{1}{n} \sum_i s_i$$

$$t_i(m) = q_i(m_{-i})y(m) + g_i(m), \text{ where}$$

$$q_i(m_{-i}) = \frac{\kappa}{n} + z_{i+1} - z_{i+2}$$

$$g_i(m) = z_i(s_i - s_{i+1})^2 - z_{i+1}(s_{i+1} - s_{i+2})^2$$

Notes:

- Implements Lindahl using two dimensions
- $g_i = 0$  in equilibrium
- Agents are 'price-taking'

$$m_i = (s_i, z_i) \in \mathbb{R}^2$$

$$y(m) = \sum_i s_i$$

$$t_i(m) = q_i(m_{-i})y(m) + g_i(m), \text{ where}$$

$$q_i(m_{-i}) = \frac{\kappa}{n} - \sum_{j \neq i} s_j + \frac{1}{n} \sum_{j \neq i} z_j$$

$$g_i(m) = -\frac{1}{2} (z_i - y(m))^2$$

Notes:

- Implements Lindahl using two dimensions
- $g_i = 0$  in equilibrium
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$$m_i = (s_i, z_i) \in \mathbb{R}^2$$

$$y(m) = \sum_i s_i$$

$$t_i(m) = q_i(m_{-i})y(m) + g_i(m), \text{ where}$$

$$q_i(m_{-i}) = \frac{\kappa}{n} - \gamma \sum_{j \neq i} s_j + \frac{\gamma}{n} \sum_{j \neq i} z_j$$

$$g_i(m) = -\frac{1}{2} (z_i - y(m))^2 + \frac{\delta}{2} \sum_{j \neq i} (z_j - y(m))^2$$

Notes:

- Implements Lindahl using two dimensions
- $g_i = 0$  in equilibrium
- Agents are 'price-taking'

## Others...

Other mechanisms:

- de Trenqualye 1989
- Vega-Redondo 1989
- Kim 1996
- Corchon & Wilkie 1996

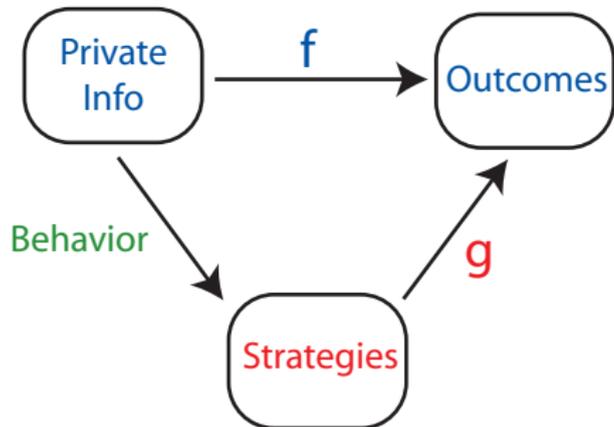
In all of these...

- Implement Lindahl using two dimensions
- $g_i = 0$  in equilibrium
- Agents are 'price-taking'

## Other Solution Concepts

- Moore & Repullo: SPNE
- Palfrey & Srivistava: Undominated NE
- Bergemann & Valimaki, Morris & Shin: Ex-post NE

# Behavioral Mechanism Design



# BMD: Methodology

When to use BMD?

- ① Theory provides too many solutions
  - Multiple candidate mechanisms to compare
- ② Theory provides no solutions
  - Use mechanisms from 'similar' problems

After identifying candidate mechanisms, test them!

# BMD: Methodology

The 'testbedding' procedure

- Step 1: Identify candidate mechanism
- Step 2: Experiments, behavioral insights
- Step 3a (short-run): Modify the mechanism directly
- Step 3b (long-run): Modify the design problem and re-solve
- - New candidate mechanism
- Return to Step 2 until satisfactory

# Four Applications

## ① Public goods mechanisms

- Long-run goal
- Theory: too many solutions
- Comparison tests, behavioral insights

## ② Contracting within NASA

- Short-run goal
- Theory: too hard (no solutions)
- Develop candidate mechanism
- Test & modify

## ③ Prediction Markets

- Short- & Long-run goals
- Theory: ambiguous
- Comparison tests, behavioral insights

## ④ Matching Markets (not covered)

- Short-run goals (so far)
- Theory: multiple solutions, trade-offs
- Comparison tests